"Fully Incremental LCS Computation"

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Longest Common Subsequence

□ A string obtained by removing 0 or more characters from string *A* is called a *subsequence* of *A*.

 The longest subsequence that occurs in both strings *A* and *B* is called the *longest common subsequence* (*LCS*) of *A* and *B*.

> $A: \times b \times c \times a$ a b a $B: b c \times a$ b a \Box LCS(*A*,*B*) = b c a b a

LCS is a common metric for sequence comparison.

Dynamic Programming

 LCS (and its length) of strings *A* and *B* can be computed by dynamic programming approach.

Fully Incremental LCS Problem

 Given LCS(*A*,*B*) and character *c*, compute LCS(*cA*,*B*), LCS(*Ac*,*B*), LCS(*A*,*cB*) and LCS(*A*,*Bc*).

◆ So we are able to e.g. process log files backdating to the past, and compute alignments between suffixes of one and the other.

 Naïve use of *DP* table takes *O*(*mn*) time for computing LCS(*cA*,*B*) and LCS(*A*,*cB*) from LCS(*A*,*B*).

◆ More efficiently!?

Landau et al. presented an algorithm that computes $LCS(cA,B)$ in $O(L)$ *time*, where $L = LCS(A,B)$.

 This work: *efficient computation for* LCS(*A*,*cB*), LCS(*Ac*,*B*) *and* LCS(*A*,*Bc*)

Fully Incremental LCS Problem [cont.]

Fully Incremental LCS Problem [cont.]

Time and Space Comparison (fixed alphabet)

 $L = LCS(A,B) \leq min(m,n)$

Our Approach

- The algorithm of Laudau et al. computes LCS(*cA*,*B*) in *O*(*L*) time.
- \Box Their algorithm does not compute the whole DP matrix $$ it only considers the set *P* of *partition points*.
- Based on their algorithm, we compute LCS(*A*,*cB*) in *O*(*n*) time by considering *partition points* only.
- Suppose we have computed *DP* for strings *A* and *B*. Let us denote by *DPBh* the DP matrix that is obtained from *DP* after we add a new character to the head (left) of *B*. Same for *PBh* and *P*.

Match Point & Partition Point

 \Box Pair (i, j) is said to be a **match point** if $A[j] = B[i]$. Pair (*i*, *j*) is said to be a *partition point* if $DP[i, j] = DP[i-1, j] + 1$.

Match Point & Partition Point [cont.]

 The set of partition points of *DP* is denoted by *P*. If (i, j) is a partition point with score v , we write as $P[v, j] = i$.

Computing **LCS(***A***,***cB***)**

□ There are no changes to the partition points until the 1st occurrence of "b" in *A*.

 All the cells in the 1st row of *DPBh* after the first occurrence of "b" get score 1.

E At most one partition point is eliminated at each column.

Eliminated Partition Point

 Lemma 1. For any column *j*, there exists row index *E^j* s.t. $DP^{Bh}[i, j] = DP[i, j] + 1$ for $i < E_j$, *DP^{Bh}*[*i*, *j*] = *DP*[*i*, *j*] for $i \ge E_j$.

(*Ej*, *j*) is the partition point to be eliminated in *DPBh*.

 \Box Lemma 2. Let $(E_{j-1}, j-1)$ and (E_j, j) be the partition points eliminated at columns j -1 and j , resp. Let $DP[E_{j-1}, j-1] = v$. Then,

 $E_{j-1} \le E_j \le P^{Bh}[v+1, j-1].$

 \Box Lemma 3-1. If there is no match point (x, j) such that *PBh*[ν , *j*-1] < $x \le E_{i-1}$,

Lemma 3-2. Otherwise,

 $E_i = P[v+1, j].$

 Due to Lemma 3-1 and 3-2, the partition points to be eliminated in *DPBh* can be computed by processing the columns of *DP* from left to right.

□ The remaining thing is how to judge whether there exists a partition point (x, j) such that $P^{Bh}[v, j-1] \le x \le E_{j-1}$ at each column *j*. *Next Match Table*

Next Match Table

 NextMatch[*i*, *c*] returns the first occurrence of "*c*" after position *i* in string *B*, if such exists. Otherwise, it returns *null*.

 Using *NextMatch* table we can check *PBh*[*v*, *j*-1] < *x* < *E^j*-1 in constant time.

Update Next Match Table

When we get a new character to the head of *B*…

<u>□ For fixed alphabet Σ it takes constant time.</u>

*Complexity for Computing LCS***(***A, cB***)**

- When updating *DP* to *DPBh*, at most *n* partition points are newly added, and at most *n* partition points are eliminated.
- Using *NextMatch* Table, each eliminated partition point can be found in *O*(1) time.
- *NextMatch* table can be updated in *O*(1) time.

Conclusion: LCS(*A*, *cB*) *can be computed from* LCS(*A*, *B*) *in O*(*n*) *time*.

Computing **LCS(***Ac***,***B***)**

 If there exist match points between *P*[*v*-1, *n*] and *P*[*v*,*n*], the uppermost match point becomes the new partition point of score *v* at column *n+*1.

 Since there are *L* intervals to be checked at column *n*+1, it takes *O*(*L*) *time* (we can use *NextMatch* table).

Computing **LCS(***A***,***Bc***)**

 New partition points at row *m*+1 can be computed in the same way as the standard DP approach.

 There are *n* columns to be checked at row *m*+1. Therefore *O*(*n*) *time*.

Update Next Match Table

When we get a new character to the tail of *B*…

 There can be at most *m* entries to be updated in *NextMatch* table. But the amortized time complexity for each new character is *constant*.

Conclusion & Future Work

□ Given LCS(A,B), the proposed algorithm computes ◆ LCS(*cA*, *B*) in *O*(*L*) time, ◆ LCS(*Ac*, *B*) in *O*(*L*) time, ◆ LCS(*A*, *cB*) in *O*(*n*) time, and ◆ LCS(*A*, *Bc*) in *O*(*n*) time, including (amortized) constant time update of *NextMatch*.

D Possible future work would be to extend our algorithm to compressed strings - fully incremental LCS computation *without decompression*. Run-length encoding?