"Fully Incremental LCS Computation"

15th International Symposium on Fundamentals on Computing Theory (FCT'05), 17-20 August 2005, Luebeck, Germany

Yusuke Ishida, <mark>Shunsuke Inenaga</mark>, Masayuki Takeda Kyushu Univ., Japan &

> Ayumi Shinohara Tohoku Univ., Japan

Longest Common Subsequence

- □ A string obtained by removing 0 or more characters from string *A* is called a *subsequence* of *A*.
- □ The longest subsequence that occurs in both strings A and B is called the longest common subsequence (LCS) of A and B.

A: xbxcxxaba

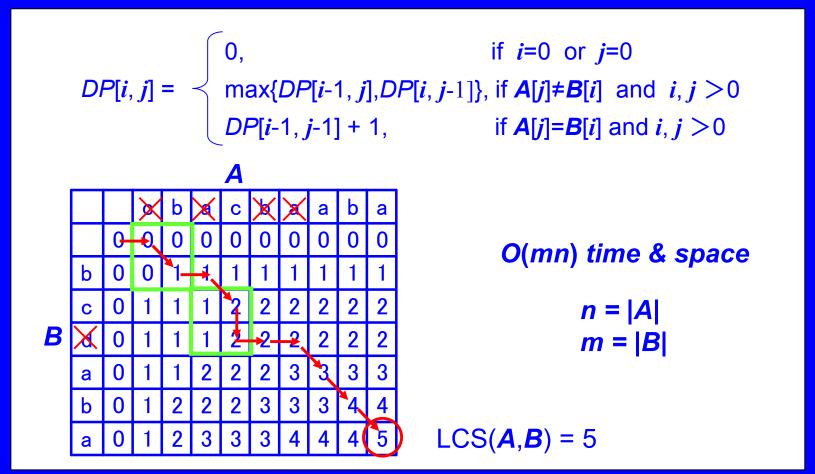
B: bc Xaba

$$LCS(A,B) = b c a b a$$

□ LCS is a common metric for sequence comparison.

Dynamic Programming

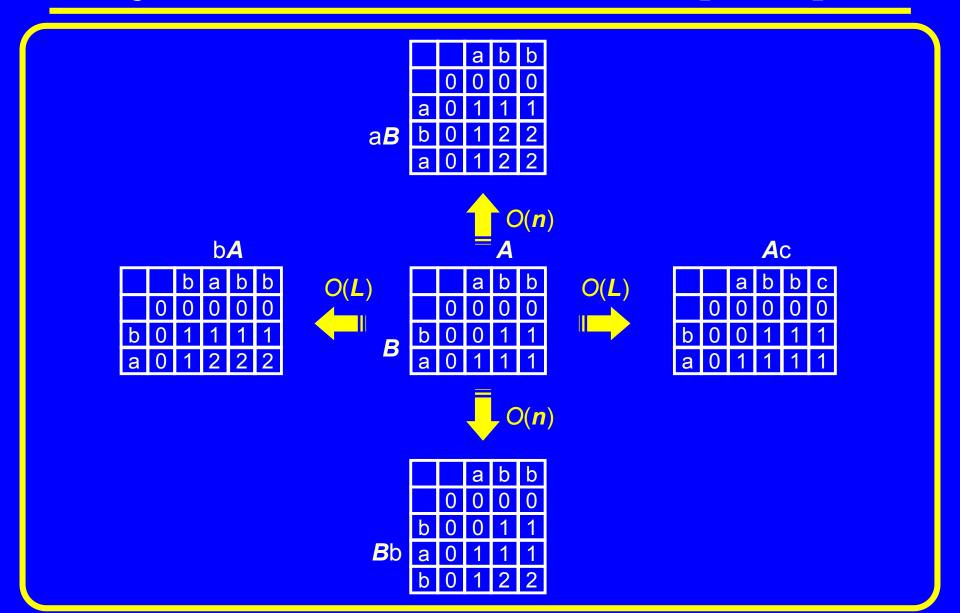
LCS (and its length) of strings **A** and **B** can be computed by dynamic programming approach.



Fully Incremental LCS Problem

- □ Given LCS(A,B) and character c, compute LCS(cA,B), LCS(Ac,B), LCS(A,CB) and LCS(A,Bc).
 - So we are able to e.g. process log files backdating to the past, and compute alignments between suffixes of one and the other.
- □ Naïve use of *DP* table takes O(mn) time for computing LCS(cA,b) and LCS(A,cb) from LCS(A,b).
 - More efficiently!?
- Landau et al. presented an algorithm that computes LCS(cA,B) in O(L) time, where L = LCS(A,B).
- □ This work: efficient computation for LCS(A,cB), LCS(Ac,B) and LCS(A,Bc)

Fully Incremental LCS Problem [cont.]



Fully Incremental LCS Problem [cont.]

Time and Space Comparison (fixed alphabet)

	Naïve DP	Modified algo. of Kim & Park	Our algorithm
LCS(cA , B)	O(mn)	O(m + n)	O(L)
LCS(Ac , B)	O(m)	O(m)	O(L)
LCS(A , cB)	O(mn)	O(m + n)	O(n)
LCS(A , Bc)	O(n)	O(n)	O(n)
Total space	O(mn)	O(mn)	O(nL + m)

 $L = LCS(A,B) \le min(m,n)$

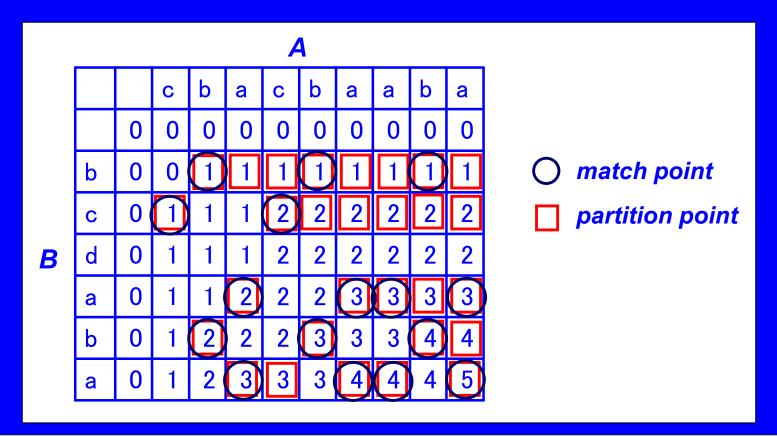
Our Approach

- □ The algorithm of Laudau et al. computes LCS(cA,B) in O(L) time.
- Their algorithm does not compute the whole DP matrix it only considers the set P of partition points.

- Based on their algorithm, we compute LCS(A,cB) in O(n) time by considering partition points only.
- □ Suppose we have computed *DP* for strings *A* and *B*. Let us denote by *DP*^{Bh} the DP matrix that is obtained from *DP* after we add a new character to the head (left) of *B*.
- \square Same for P^{Bh} and P.

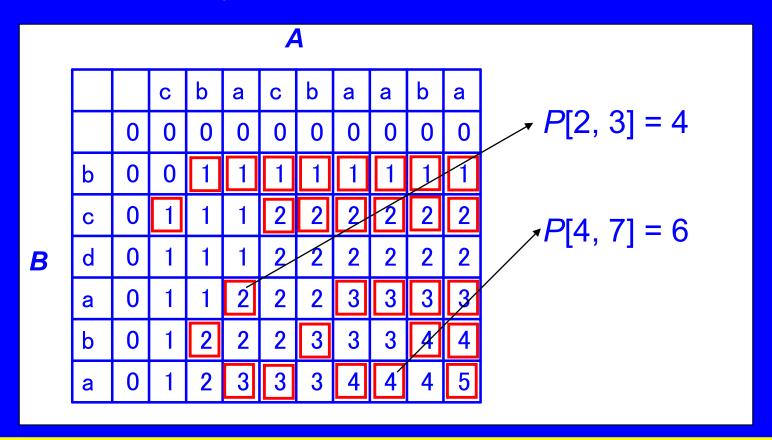
Match Point & Partition Point

- \square Pair (i, j) is said to be a **match point** if A[j] = B[i].
- □ Pair (i, j) is said to be a **partition point** if DP[i, j] = DP[i-1, j] + 1.

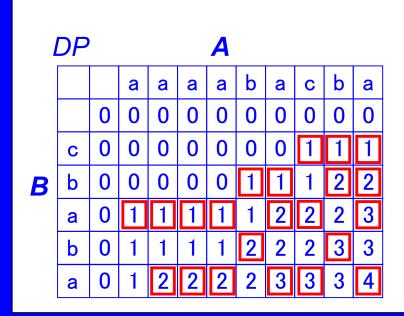


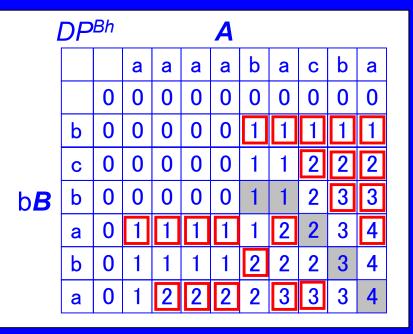
Match Point & Partition Point [cont.]

- □ The set of partition points of DP is denoted by P.
- If (i, j) is a partition point with score v, we write as P[v, j] = i.



Computing LCS(A,cB)





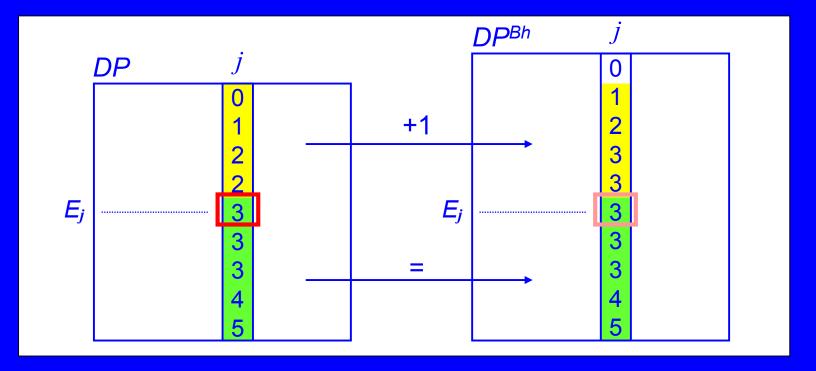
- □ There are no changes to the partition points until the 1st occurrence of "b" in **A**.
- □ All the cells in the 1st row of *DP*^{Bh} after the first occurrence of "b" get score 1.
- At most one partition point is eliminated at each column.

Eliminated Partition Point

Lemma 1. For any column j, there exists row index E_j s.t.

$$DP^{Bh}[i, j] = DP[i, j] + 1 \text{ for } i < E_j,$$

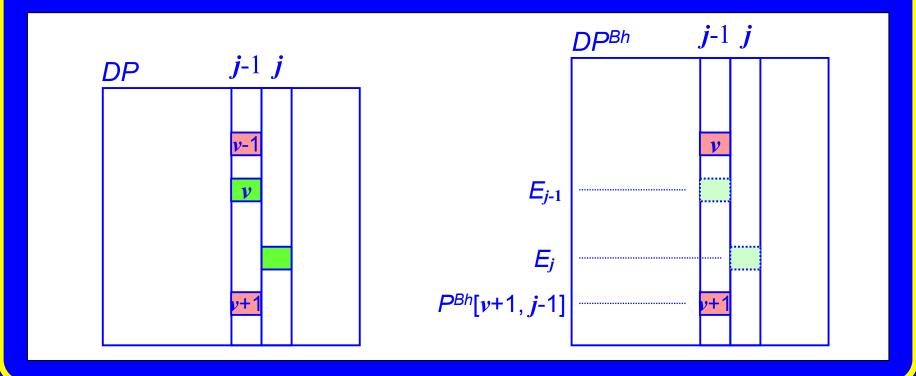
 $DP^{Bh}[i, j] = DP[i, j] \text{ for } i \ge E_j.$



 \square (E_i, j) is the partition point to be eliminated in DP^{Bh} .

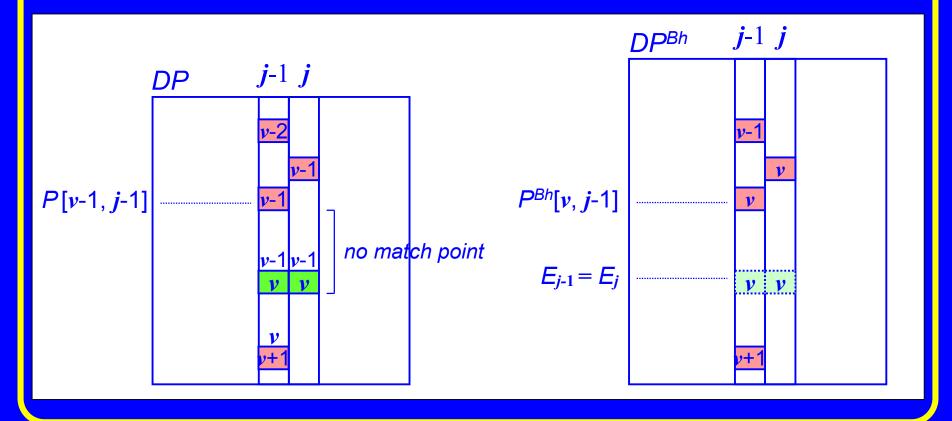
Lemma 2. Let $(E_{j-1}, j-1)$ and (E_j, j) be the partition points eliminated at columns j-1 and j, resp. Let $DP[E_{j-1}, j-1] = v$. Then,

$$E_{j-1} \leq E_j \leq P^{Bh}[v+1, j-1].$$



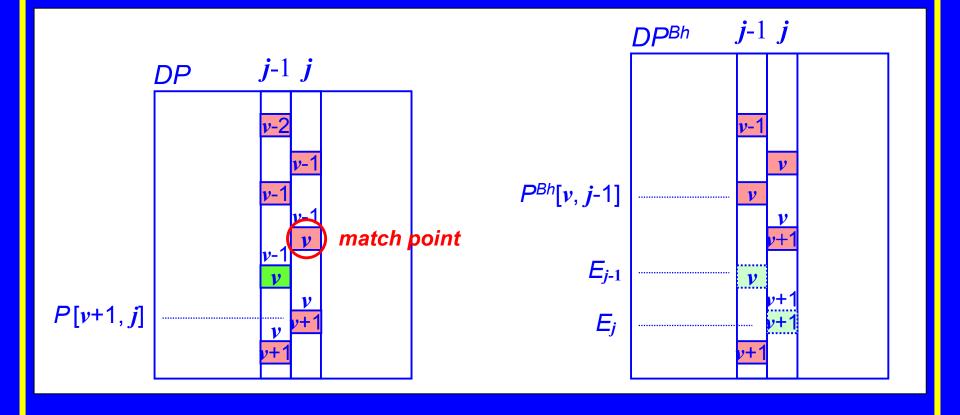
Lemma 3-1. If there is no match point (x, j) such that $P^{Bh}[v, j-1] < x \le E_{j-1}$,

$$E_j = E_{j-1}$$



□ Lemma 3-2. Otherwise,

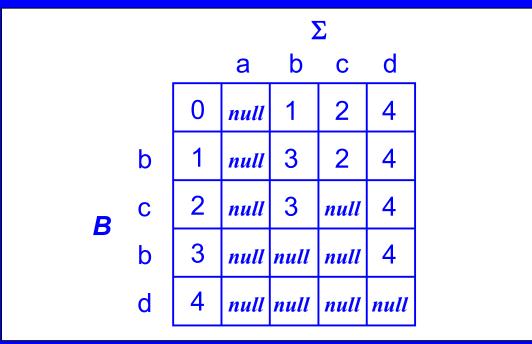
$$E_j = P[v+1, j].$$



- □ Due to Lemma 3-1 and 3-2, the partition points to be eliminated in *DP*^{Bh} can be computed by processing the columns of *DP* from left to right.
- The remaining thing is how to judge whether there exists a partition point (x, j) such that $P^{Bh}[v, j-1] < x \le E_{j-1}$ at each column j. Next Match Table

Next Match Table

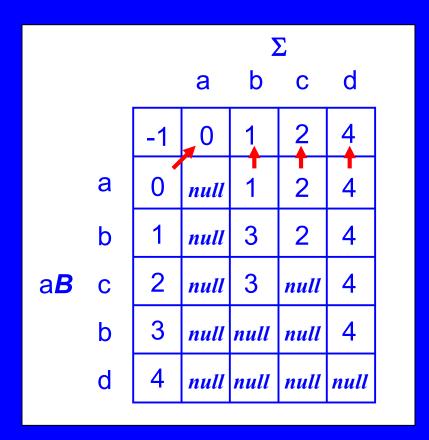
NextMatch[i, c] returns the first occurrence of "c" after position i in string B, if such exists. Otherwise, it returns null.



Using NextMatch table we can check $P^{Bh}[v, j-1] < x \le E_{j-1}$ in constant time.

Update Next Match Table

□ When we get a new character to the head of **B**...



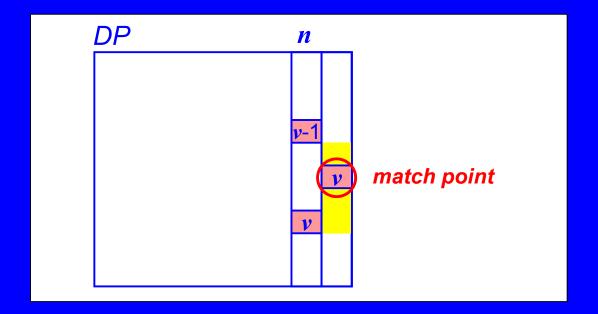
 \square For fixed alphabet Σ it takes constant time.

Complexity for Computing LCS(A, cB)

- □ When updating **DP** to **DP**^{Bh}, at most **n** partition points are newly added, and at most **n** partition points are eliminated.
- □ Using *NextMatch* Table, each eliminated partition point can be found in *O*(1) time.
- □ NextMatch table can be updated in O(1) time.
- □ Conclusion: LCS(A, cB) can be computed from LCS(A, B) in O(n) time.

Computing LCS(Ac,B)

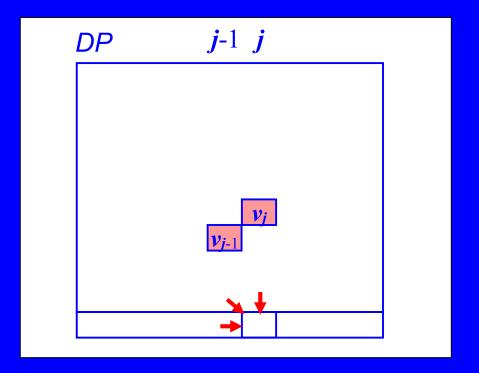
If there exist match points between P[v-1, n] and P[v,n], the uppermost match point becomes the new partition point of score v at column n+1.



□ Since there are L intervals to be checked at column n+1, it takes O(L) time (we can use NextMatch table).

Computing LCS(A,Bc)

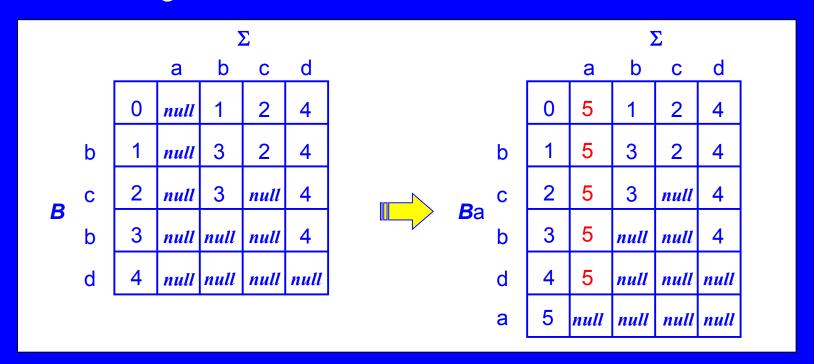
■ New partition points at row m+1 can be computed in the same way as the standard DP approach.



□ There are n columns to be checked at row m+1. Therefore O(n) time.

Update Next Match Table

□ When we get a new character to the tail of **B**...



□ There can be at most *m* entries to be updated in NextMatch table. But the amortized time complexity for each new character is constant.

Conclusion & Future Work

- □ Given LCS(**A**,**B**), the proposed algorithm computes
 - \leftarrow LCS(cA, B) in O(L) time,
 - \leftarrow LCS(Ac, B) in O(L) time,
 - \leftarrow LCS(\boldsymbol{A} , \boldsymbol{cB}) in $O(\boldsymbol{n})$ time, and
 - \leftarrow LCS(\boldsymbol{A} , \boldsymbol{Bc}) in $O(\boldsymbol{n})$ time,

including (amortized) constant time update of NextMatch.

□ Possible future work would be to extend our algorithm to compressed strings - fully incremental LCS computation without decompression. Run-length encoding?